



PROBLEM 5.3:

$$y[n] = 2x[n] - 3x[n-1] + 2x[n-2]$$

(a) MAKE A TABLE:

n	< 0	0	1	2	3	4	5	6	7	≥ 8
x[n]	0	1	2	3	2	1	1	1	1	1
y[n]	0	2	1	2	-1	2	3	1	1	1

$$y[0] = 2x[0] - 3x[-1] + 2x[-2] = 2(1) = 2$$

$$y[1] = 2x[1] - 3x[0] + 2x[-1] = 2(2) - 3(1) = 1$$

$$y[2] = 2x[2] - 3x[1] + 2x[0] = 2(3) - 3(2) + 2(1) = 2$$

$$y[3] = 2(2) - 3(3) + 2(2) = -1$$

$$y[4] = 2(1) - 3(2) + 2(3) = 2$$

$$y[5] = 2(1) - 3(1) + 2(2) = 3$$

$$y[6] = 2(1) - 3(1) + 2(1) = 1$$

$$y[7] = 2(1) - 3(1) + 2(1) = 1$$

$$y[8] = 2(1) - 3(1) + 2(1) = 1$$

(c) Impulse Response

$$h[0] = 2(1) - 3(0) + 2(0) = 2$$

$$h[1] = 2(0) - 3(1) + 2(0) = -3$$

$$h[2] = 2(0) - 3(0) + 2(0) = 2$$

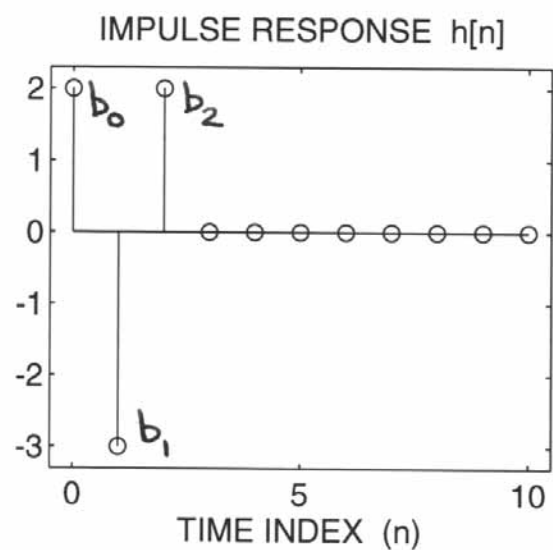
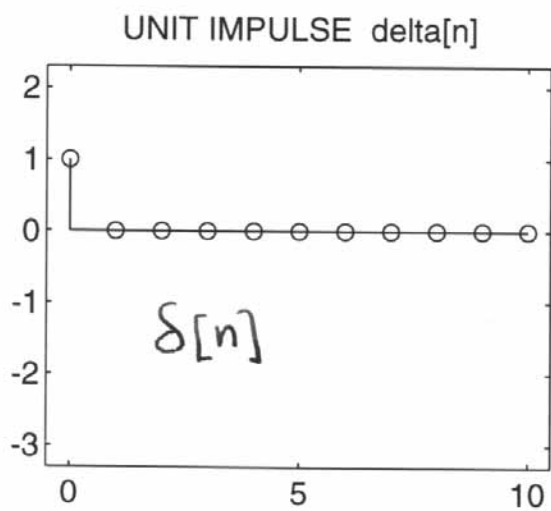
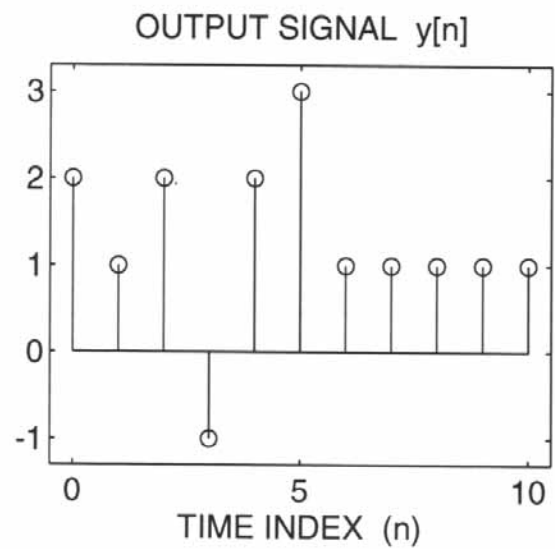
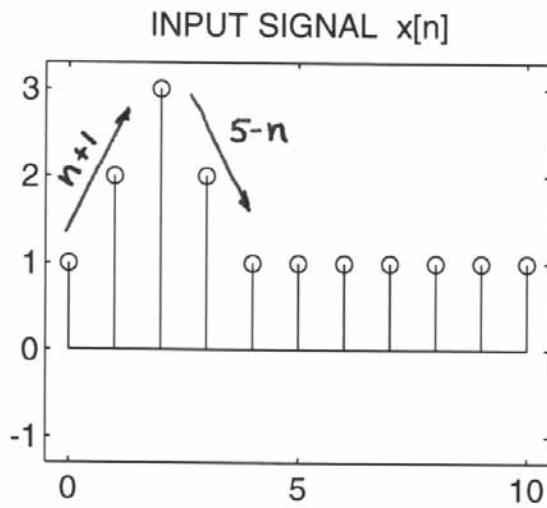
Notice $h[n]$ just "reads out" the filter coefficients:

i.e., $h[n] = b_n$



PROBLEM 5.3 (more):

Plots via MATLAB





PROBLEM 5.6:

Plots for parts (a), (b) and (c) are below.
 (d) This general solution will also apply to part (c).

$$x[n] = a^n u[n] \quad y[n] = \frac{1}{L} \sum_{k=0}^{L-1} x[n-k] = \frac{1}{L} \sum_{k=0}^{L-1} a^{n-k} u[n-k]$$

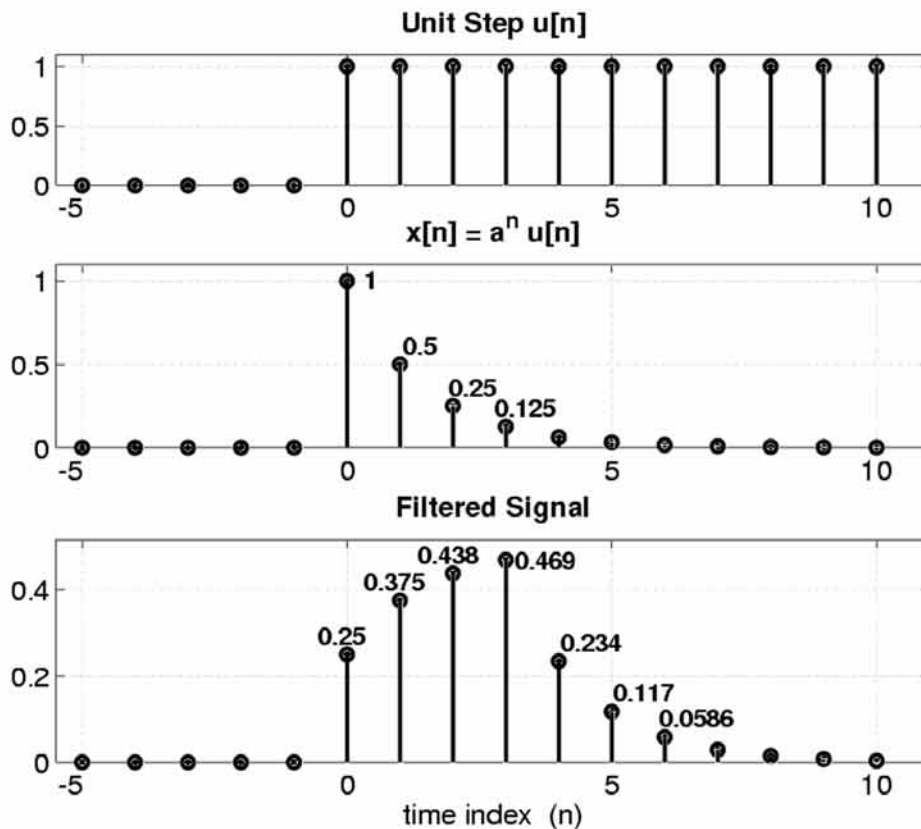
There are 3 cases.

1. $n < 0 \Rightarrow y[n] = 0$ because $u[n-k]$ is always zero

2. $0 \leq n \leq L-1$ $y[n] = \frac{1}{L} \sum_{k=0}^n a^{n-k} u[n-k] = \frac{a^n}{L} \sum_{k=0}^n a^{-k}$

$\Rightarrow y[n] = \frac{a^n}{L} \left(\frac{1 - a^{n+1}}{1 - a^{-1}} \right) = \frac{1}{L} \left(\frac{a^{n+1} - 1}{a - 1} \right)$

3. $n \geq L$ $y[n] = \frac{1}{L} \sum_{k=0}^{L-1} a^{n-k} u[n-k] = \frac{a^n}{L} \sum_{k=0}^{L-1} a^{-k}$
 $= \frac{a^n}{L} \left(\frac{1 - a^{-L}}{1 - a^{-1}} \right) = \frac{a^n}{L} \left(\frac{a^L - 1}{a^L - a^{L-1}} \right)$ for $n \geq L$.



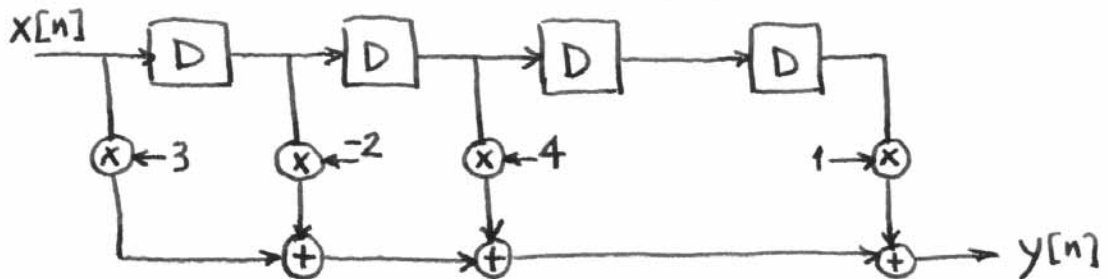
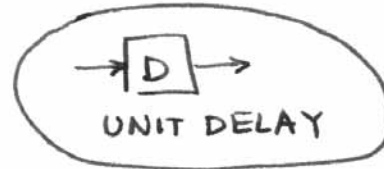


PROBLEM 5.11:

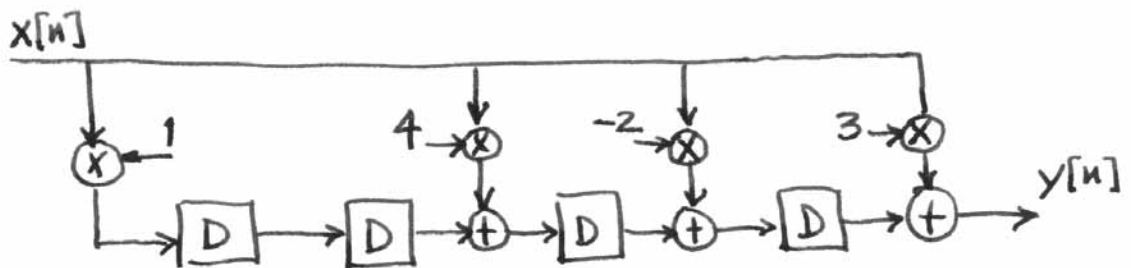
$$h[n] = 3\delta[n] - 2\delta[n-1] + 4\delta[n-2] + \delta[n-4]$$

$$\Rightarrow y[n] = 3x[n] - 2x[n-1] + 4x[n-2] + x[n-4]$$

(a) Direct Form:



(b) Transposed Direct Form:





PROBLEM 5.14:

(a) $h[n] = \delta[n-2] \Rightarrow$ filter is a delay by 2

$$y[n] = u[n-3] - u[n-6]$$

To find $x[n]$ we need to "un-delay" $y[n]$.

$$\Rightarrow x[n] = u[n-1] - u[n-4]$$

(b) First-difference FIR $\Rightarrow h[n] = \delta[n] - \delta[n-1]$

The first-difference filter has a nonzero output at n when $x[n] \neq x[n-1]$ are not equal.

If $y[n] = \delta[n] - \delta[n-4]$, then the input $x[n]$ changes value at $n=0$ and $n=4$. At $n=0$, it jumps up by one; at $n=4$, it jumps down.

$$\Rightarrow x[n] = u[n] - u[n-4]$$

jump up by one

jump down

(c) 4-pt averager: $y[n] = \frac{1}{4}(x[n] + x[n-1] + x[n-2] + x[n-3])$

$$\text{If } y[n] = -5\delta[n] - 5\delta[n-2]$$

$$y[0] = -5 = \frac{1}{4}(x[0] + x[-1] + x[-2] + x[-3])$$

** if we assume $x[n]=0$ for $n < 0$, then $x[0] = -20$

$$y[1] = 0 = \frac{1}{4}(x[1] + x[0] + x[-1] + x[-2]) = \frac{1}{4}x[1] - 5$$

$$\Rightarrow x[1] = 20$$

$$\left. \begin{aligned} y[2] = -5 &= \frac{1}{4}(x[2] + x[1] + x[0] + x[-1]) \\ &= \frac{1}{4}(x[2] + 20 - 20 + 0) = \frac{1}{4}x[2] \end{aligned} \right\} x[2] = -20$$

$$y[3] = 0 = \frac{1}{4}(x[3] + x[2] + x[1] + x[0]) \Rightarrow x[3] = -20$$

$$\Rightarrow x[n] = \begin{cases} 0 & \text{for } n < 0 \\ -20 & \text{for } n \text{ even} \\ 20 & \text{for } n \text{ odd} \end{cases}$$



PROBLEM 5.17:

$$\begin{aligned} \text{(a)} \quad h_1[n] &= \delta[n] - \delta[n-1] \\ h_2[n] &= \delta[n] + \delta[n-2] \\ h_3[n] &= \delta[n-1] + \delta[n-2] \end{aligned}$$

(b) The overall $h[n]$ is the convolution of the $h_i[n]$.

$$\begin{aligned} h[n] &= h_1[n] * h_2[n] * h_3[n] \\ h_1[n] * h_2[n] &= (\delta[n] - \delta[n-1]) * (\delta[n] + \delta[n-2]) \\ &= \delta[n] - \delta[n-1] + \delta[n-2] - \delta[n-3] \end{aligned}$$

Now convolve with $h_3[n]$

$$\begin{array}{cccccccc} 1 & -1 & 1 & -1 & & & & \\ 0 & 1 & 1 & & & & & \\ \hline 0 & 0 & 0 & 0 & & & & \\ & & 1 & -1 & 1 & -1 & & \\ \hline & & & 1 & -1 & 1 & -1 & \\ 0 & 1 & 0 & 0 & 0 & 0 & -1 & \\ \hline n=0 & \uparrow n=1 & & & & & \uparrow n=5 & \end{array}$$

$$h[n] = \delta[n-1] - \delta[n-5]$$

$$\begin{aligned} \text{(c)} \quad y[n] &= h[n] * x[n] \\ &= (\delta[n-1] - \delta[n-5]) * x[n] \\ y[n] &= x[n-1] - x[n-5] \end{aligned}$$



PROBLEM 6.3:

$$y[n] = x[-n]$$

$$(a) x[n] = Ae^{j\varphi} e^{j\hat{\omega}n}$$

$$y[n] = Ae^{j\varphi} e^{j\hat{\omega}(-n)} = Ae^{j\varphi} e^{-j\hat{\omega}n}$$

(b) NO.

The output cannot be written as

$$y[n] = \mathcal{H}(\hat{\omega}) Ae^{j\varphi} e^{j\hat{\omega}n}$$

because the frequency has changed from $+\hat{\omega}$ to $-\hat{\omega}$.



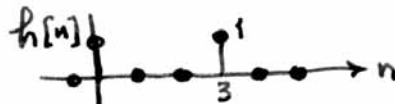
PROBLEM 6.8:

$$\begin{aligned}
 (a) \quad H(\hat{\omega}) &= (1 + e^{-j\hat{\omega}}) \left(1 - \underbrace{2 \cos\left(\frac{2\pi}{3}\right)}_{=2(1/2)=1} e^{-j\hat{\omega}} + e^{-j2\hat{\omega}} \right) \\
 &= (1 + e^{-j\hat{\omega}}) (1 - e^{-j\hat{\omega}} + e^{-j2\hat{\omega}}) \\
 &= 1 - e^{-j\hat{\omega}} + e^{-j2\hat{\omega}} + e^{-j\hat{\omega}} - e^{-j2\hat{\omega}} + e^{-j3\hat{\omega}} \\
 &= 1 + e^{-j3\hat{\omega}}
 \end{aligned}$$

Difference Equation:

$$y[n] = x[n] + x[n-3]$$

(b) When $x[n] = \delta[n]$, $y[n] = \delta[n] + \delta[n-3]$



← This is $h[n]$, the impulse response

(c) Need to find where $H(\hat{\omega}) = 0$.

$$1 + e^{-j3\hat{\omega}} = 0$$

$$e^{-j3\hat{\omega}} = -1 = e^{j\pi} e^{j2\pi l}$$

$$\Rightarrow e^{j\hat{\omega}} = e^{-j\pi/3} e^{-j2\pi l/3}$$

$$\Rightarrow \hat{\omega} = -\frac{\pi}{3} - \frac{2\pi}{3}l \quad l=0, 1, 2.$$

$$\hat{\omega} = -\frac{\pi}{3}, -\pi, \text{ and } -\frac{5\pi}{3} \leftarrow \text{same as } +\frac{\pi}{3}$$

$$y[n] = H(\hat{\omega}) A e^{j4} e^{j\hat{\omega}n}$$

Thus when $H(\hat{\omega}) = 0$, the output is zero.



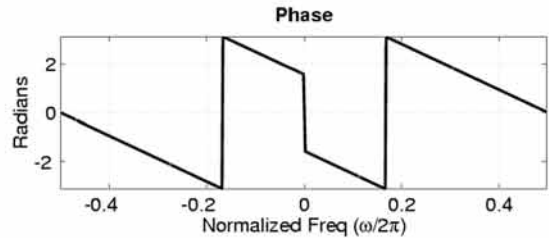
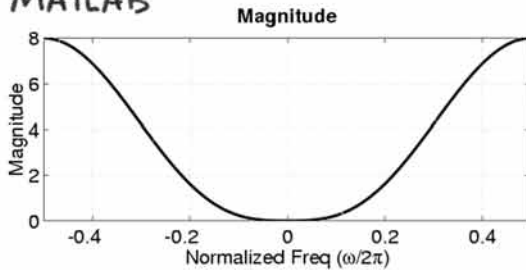
PROBLEM 6.12:

$$y[n] = x[n] - 3x[n-1] + 3x[n-2] - x[n-3]$$

(a) use filter coeffs: $\{b_k\} = \{1, -3, 3, -1\}$

$$\begin{aligned} \mathcal{H}(\hat{\omega}) &= 1 - 3e^{-j\hat{\omega}} + 3e^{-j2\hat{\omega}} - e^{-j3\hat{\omega}} = (1 - e^{-j\hat{\omega}})^3 \\ &= e^{-j3\hat{\omega}/2} \left(\frac{e^{j\hat{\omega}/2} - e^{-j\hat{\omega}/2}}{(2j)^3} \right)^3 (2j)^3 \quad \left(2e^{j\pi/2} \right)^3 = 8e^{-j\pi/2} \\ &= 8e^{j(-\pi/2 - 3\hat{\omega}/2)} \sin^3(\hat{\omega}/2) \end{aligned}$$

(b) MATLAB



(c) $x[n] = 10 + 4 \cos(\frac{\pi}{2}n + \frac{\pi}{4})$

$$y[n] = 10\mathcal{H}(0) + 4|\mathcal{H}(\frac{\pi}{2})| \cos(\frac{\pi}{2}n + \frac{\pi}{4} + \angle\mathcal{H}(\frac{\pi}{2}))$$

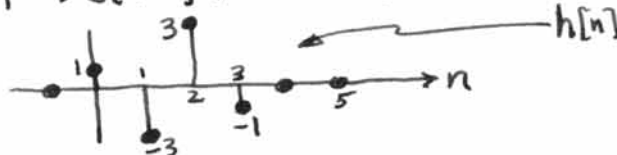
$$\begin{aligned} \mathcal{H}(\frac{\pi}{2}) &= 8e^{-j(\pi/2 + 3\pi/4)} \sin^3(\frac{\pi}{4}) \\ &= 8(\frac{\sqrt{2}}{2})^3 e^{-j5\pi/4} = 2\sqrt{2} e^{-j5\pi/4} \end{aligned}$$

$$\mathcal{H}(0) = 0$$

$$\begin{aligned} \Rightarrow y[n] &= 10(0) + 8\sqrt{2} \cos(\frac{\pi}{2}n + \frac{\pi}{4} - \frac{5\pi}{4}) \\ &= 8\sqrt{2} \cos(\frac{\pi}{2}n - \pi) \end{aligned}$$

(d) $x[n] = \delta[n]$

$$y[n] = \delta[n] - 3\delta[n-1] + 3\delta[n-2] - \delta[n-3]$$



(e) Use superposition, so just add the results from (c) and (d)

$$y[n] = 8\sqrt{2} \cos(\frac{\pi}{2}n - \pi) + \delta[n] - 3\delta[n-1] + 3\delta[n-2] - \delta[n-3]$$



PROBLEM 6.15:

$$x(t) = 10 + 8 \cos(200\pi t) + 6 \cos(500\pi t + \pi/4)$$

$$f_s = 1000$$

$$x[n] = x(t) \Big|_{t=n/f_s = n/1000}$$

$$= 10 + 8 \cos\left(200 \frac{\pi n}{1000}\right) + 6 \cos\left(\frac{500\pi n}{1000} + \pi/4\right)$$

$$= 10 + 8 \cos(0.2\pi n) + 6 \cos(0.5\pi n + \pi/4)$$

$$\begin{array}{ccc} \nearrow & \uparrow & \longleftarrow \\ \text{Need } H(0) & \text{Need } H(0.2\pi) & H(0.5\pi) = 0 \end{array}$$

Use frequency response values from Prob. 6.14

$$H(0) = 1 \quad H(0.2\pi) = 0.769 e^{-j0.3\pi}$$

$$y[n] = 10 + (0.769) 8 \cos(0.2\pi n - 0.3\pi)$$

$$= 10 + 6.156 \cos(0.2\pi n - 0.3\pi)$$

$$y(t) = y[n] \Big|_{n \leftarrow \frac{f_s}{t} = 1000t}$$

$$= 10 + 6.156 \cos(200\pi t - 0.3\pi)$$



PROBLEM 6.20:

(a) The highest frequency in $x(t)$ is $\omega_0 = 2\pi(500)$
 To avoid aliasing we must sample at $f_s > 2f_{MAX}$
 $\Rightarrow f_s > 2(500\text{Hz}) = 1000 \text{ samples/sec.}$

(b) $h[n] = \delta[n-10]$, f_s and ω_0 to be determined

$$x[n] = 10 + 20 \cos(\omega_0 n / f_s + \pi/3)$$

$$y[n] = x[n-10] = 10 + 20 \cos(\omega_0 \frac{(n-10)}{f_s} + \pi/3)$$

$$y(t) = y[n] \Big|_{n \leftarrow f_s t} = 10 + 20 \cos(\frac{\omega_0}{f_s} (f_s t - 10) + \pi/3)$$

Since we want $y(t) = x(t - 0.001)$, we need

$$\frac{\omega_0}{f_s} (10) = (0.001) \omega_0$$

$$\Rightarrow 10/f_s = 1/1000 \Rightarrow f_s = 10,000 \text{ Hz}$$

In order for the output frequency to be the same as the input frequency ω_0 , there must be no aliasing. $\Rightarrow 2\omega_0 < 2\pi f_s$

$$\Rightarrow \omega_0 < 2\pi(500) \text{ rad/sec}$$

(c) To have $y(t) = A$, we need $y[n] = \text{constant.}$

Since $x[n] = 10 + 20 \cos(\omega_0 n / f_s + \pi/3)$ $f_s = 2000$

the filter must "null out" the cosine term

$$\Rightarrow \frac{\omega_0}{f_s} = \hat{\omega}_{NULL} \text{ where } \hat{\omega}_{NULL} \text{ is one of the zeros of } \mathcal{H}(\hat{\omega})$$

$$\mathcal{H}(\hat{\omega}) = 0 \text{ when } \hat{\omega} = 2\pi/5, 4\pi/5, -2\pi/5, -4\pi/5$$

$$\therefore \omega_0 = f_s \hat{\omega}_{NULL} = \{ 2\pi(400), 2\pi(800), -2\pi(400), -2\pi(800) \}$$

We must include all aliases:

$$2\pi(400), 2\pi(2400), 2\pi(4400), \dots \quad 2\pi(400 + 2000l)$$

$$2\pi(800), 2\pi(2800), 2\pi(4800), \dots \quad 2\pi(800 + 2000l)$$

$$2\pi(-400), 2\pi(1600), 2\pi(3600), \dots \quad 2\pi(-400 + 2000l)$$

$$2\pi(-800), 2\pi(1200), 2\pi(3200), \dots \quad 2\pi(-800 + 2000l)$$



PROBLEM 7.3:

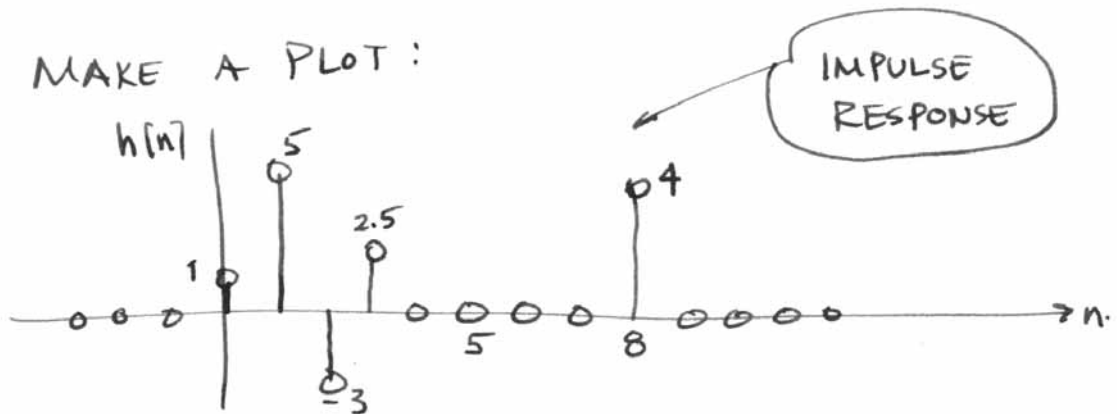
(a) $y[n] = x[n] + 5x[n-1] - 3x[n-2] + \frac{5}{2}x[n-3] + 4x[n-8]$

$$H(z) = 1 + 5z^{-1} - 3z^{-2} + \frac{5}{2}z^{-3} + 4z^{-8}$$

(b) when $x[n] = \delta[n]$, you can substitute.

$$h[n] = \delta[n] + 5\delta[n-1] - 3\delta[n-2] + \frac{5}{2}\delta[n-3] + 4\delta[n-8]$$

MAKE A PLOT:



NOTE:

The difference equation can be written as:

$$y[n] = \sum_{k=0}^M b_k x[n-k]$$

Then the impulse response will just take on the values given by the $\{b_k\}$

$$\therefore h[0] = b_0, h[1] = b_1, h[2] = b_2, \dots \text{etc.}$$



PROBLEM 7.6:

(a) $Y_1(z) = H_1(z) X(z)$

$$Y(z) = H_2(z) Y_1(z) = H_2(z) (H_1(z) X(z))$$

$$= \underbrace{(H_2(z) H_1(z))}_{H(z)} X(z) \quad \text{because } H(z) = \frac{Y(z)}{X(z)}$$

(b) Since $H_2(z) H_1(z) = H_1(z) H_2(z)$ because $H_1(z)$ and $H_2(z)$ are scalar functions.

$\Rightarrow Y(z) = H_1(z) \underbrace{H_2(z)}_{\text{means that } H_2(z) \text{ is applied first}} X(z)$

(c) $H_1(z) = \frac{1}{3}(1 + z^{-1} + z^{-2})$ by using the filter coeffs.

$$H(z) = H_2(z) H_1(z)$$

$$= \frac{1}{3}(1 + z^{-1} + z^{-2}) \cdot \frac{1}{3}(1 + z^{-1} + z^{-2})$$

$$= \frac{1}{9}(1 + 2z^{-1} + 3z^{-2} + 2z^{-3} + z^{-4})$$

(d) Convert to difference equation (i.e., filter coeffs)

$$y[n] = \frac{1}{9}(x[n] + 2x[n-1] + 3x[n-2] + 2x[n-3] + x[n-4])$$

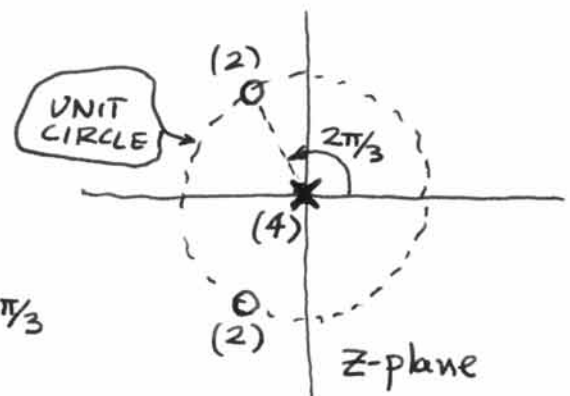
(e) Find the poles & zeros of $H_2(z)$, then "double" them because $H_1(z) = H_2(z)$.

$$H_2(z) = \frac{1}{3} z^{-2} (z^2 + z + 1)$$

$\frac{1}{z^2}$ contributes two poles at $z=0$

Zeros are:

$$\frac{-1 \pm \sqrt{1-4}}{2} = \frac{-1 \pm j\sqrt{3}}{2} = e^{\pm j2\pi/3}$$





PROBLEM 7.6 (more):

$$\begin{aligned}
 (f) \quad H(e^{j\hat{\omega}}) &= H_1(e^{j\hat{\omega}})H_2(e^{j\hat{\omega}}) \\
 &= \frac{1}{9} (1 + e^{-j\hat{\omega}} + e^{-j2\hat{\omega}})^2 \\
 &= \frac{1}{9} e^{-j2\hat{\omega}} (e^{j\hat{\omega}} + 1 + e^{-j\hat{\omega}})^2 \\
 &= \frac{1}{9} e^{-j2\hat{\omega}} (1 + 2\cos(\hat{\omega}))^2
 \end{aligned}$$

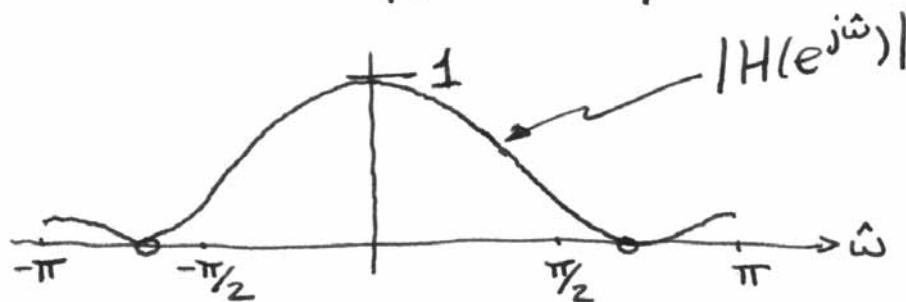
$$|H(e^{j\hat{\omega}})| = \frac{1}{9} (1 + 2\cos(\hat{\omega}))^2$$

At $\hat{\omega} = 0$, $|H| = \frac{1}{9} (3)^2 = 1$

At $\hat{\omega} = \pi/2$, $|H| = \frac{1}{9} (1)^2 = 1/9$

At $\hat{\omega} = 2\pi/3$, $|H| = 0$ because there is a zero on the unit circle.

At $\hat{\omega} = \pi$, $|H| = \frac{1}{9} (1-2)^2 = 1/9$





PROBLEM 7.12:

(a) $H(z) = (1 - z^{-1})(1 + z^{-2})(1 + z^{-1})$ MULTIPLY OUTER FACTORS
 $= (1 - z^{-2})(1 + z^{-2}) = 1 - z^{-4}$

$\therefore y[n] = x[n] - x[n-4]$

(b) $H(e^{j\hat{\omega}}) = H(z)|_{z=e^{j\hat{\omega}}} = 1 - e^{-j4\hat{\omega}}$

(c) $H(e^{j\hat{\omega}}) = e^{-j2\hat{\omega}}(e^{+j2\hat{\omega}} - e^{-j2\hat{\omega}})$
 $= 2j e^{-j2\hat{\omega}} \sin 2\hat{\omega} = (2 \sin 2\hat{\omega}) e^{j(\pi/2 - 2\hat{\omega})}$

MAG: $2 \sin 2\hat{\omega}$ ALTHOUGH THIS HAS A SIGN CHANGE FOR $\hat{\omega} < 0$
 PHASE: $\pi/2 - 2\hat{\omega}$

(d) BLOCK WHEN $H(e^{j\hat{\omega}}) = 0$

\therefore SOLVE $2 \sin 2\hat{\omega} = 0$
 $\Rightarrow \hat{\omega} = 0, \pi/2, \pi, -\pi/2$

(e) Need $H(e^{j\pi/3})$ because that is the frequency of the input.

$H(e^{j\pi/3}) = (2 \sin \frac{2\pi}{3}) e^{j(\pi/2 - 2\pi/3)}$
 $= 2(\frac{\sqrt{3}}{2}) e^{j(3\pi/6 - 4\pi/6)}$
 $= \sqrt{3} e^{-j\pi/6} = \sqrt{3} e^{j\pi} e^{-j\pi/6} = \sqrt{3} e^{j5\pi/6}$

\therefore OUTPUT IS: $y[n] = \sqrt{3} \cos(\frac{\pi n}{3} + \frac{5\pi}{6})$



PROBLEM 7.18:

(a) $H_1(z) = H_2(z) = 1 + z^{-1} + z^{-2} + z^{-3}$

(b) $H(z) = H_1(z)H_2(z) = (1 + z^{-1} + z^{-2} + z^{-3})^2$

(c) Multiply out the product:

$$H(z) = 1 + 2z^{-1} + 3z^{-2} + 4z^{-3} + 3z^{-4} + 2z^{-5} + z^{-6}$$

Invert term-by-term:

$$h[n] = \delta[n] + 2\delta[n-1] + 3\delta[n-2] + 4\delta[n-3] + 3\delta[n-4] + 2\delta[n-5] + \delta[n-6]$$

(d) Use the polynomial coeffs of $H(z)$ as filter coefficients:

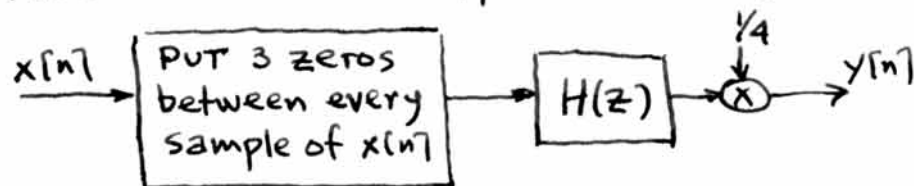
$$y[n] = x[n] + 2x[n-1] + 3x[n-2] + 4x[n-3] + 3x[n-4] + 2x[n-5] + x[n-6]$$

(e) Linear interpolation uses a triangularly shaped impulse response, which is exactly the form of $h[n]$.



There are two problems with using $h[n]$ directly: The value at the peak of the triangle is 4, not 1, so we need a scale factor of $\frac{1}{4}$. The peak value is at $n=3$, not $n=0$, so the output is time-shifted-delayed by 3.

Procedure: (to interpolate $x[n]$ by 4)



The output $y[n]$ is " $x[n]$ interpolated" but shifted by 3 samples.



PROBLEM 7.18 (more):

(f) Prove $H_1(z) = \frac{1-z^{-4}}{1-z^{-1}}$

$$\begin{aligned} (1-z^{-1})H_1(z) &= (1-z^{-1})(1+z^{-1}+z^{-2}+z^{-3}) \\ &= 1+z^{-1}+z^{-2}+z^{-3}-z^{-1}-z^{-2}-z^{-3}-z^{-4} \\ &= 1-z^{-4} \end{aligned}$$

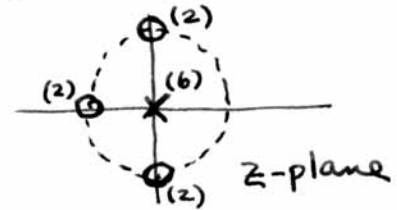
(g) $H_1(z)$ and $H_2(z)$ have the same poles & zeros so we find the poles and zeros of $H_1(z)$ and plot them "twice" in the z-plane.

$$H_1(z) = \frac{1-z^{-4}}{1-z^{-1}} = \frac{z^4-1}{z^3(z-1)}$$

← ROOTS = 1, -1, j, -j
 ← ROOTS = 0, 1

The numerator and denominator both have roots at $z=1$, so these cancel. We are left with 3 zeros at $z=-1, +j, -j$ and 3 poles at $z=0$.

⇒ $H(z)$ has 6 zeros; two each at $z=-1, +j$ and $-j$
 $H(z)$ has 6 poles at $z=0$



(h) $H_1(e^{j\hat{\omega}}) = H_1(z)|_{z=e^{j\hat{\omega}}}$

$$\begin{aligned} &= \frac{1-e^{-j4\hat{\omega}}}{1-e^{-j\hat{\omega}}} = \frac{e^{-j2\hat{\omega}}}{e^{-j\hat{\omega}/2}} \cdot \frac{(e^{j2\hat{\omega}} - e^{-j2\hat{\omega}})(\frac{1}{2j})}{(e^{j\hat{\omega}/2} - e^{-j\hat{\omega}/2})(\frac{1}{2j})} \\ &= e^{-j3\hat{\omega}/2} \frac{\sin(2\hat{\omega})}{\sin(\frac{1}{2}\hat{\omega})} \end{aligned}$$

(i) $H(e^{j\hat{\omega}}) = H_1^2(e^{j\hat{\omega}}) \rightarrow e^{-j3\hat{\omega}} \left(\frac{\sin(2\hat{\omega})}{\sin(\frac{1}{2}\hat{\omega})} \right)^2$

